Ref #	Hits	Search Query	DBs	Default Operat or	Plura Is	Time Stamp
[1:1]	6518	("382103,104,106,107"). PN. or ((340/435,477,686. 9,961,988,990) or (701/96,117,300,301)). CCLS.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	OFF	2005/11/01 10:31
L2	5427	1 and (recogni\$4 or detect\$4 or identif\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:31
L3.	1861	2 and (camera\$3 or CCD or video\$3 or captur\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR ,	ON	2005/11/01 10:31
L4	1760	3 and (calculat\$4 or comput\$4 or measur\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:35

L5	1552	4 and distanc\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:32
L6	663	5 and target\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:32
L7		6 and compress\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:32
L8	26310	("382103,104,106,107, 166,232,233,235,243, 244").PN. or ((340/435, 477,686.9,961,988,990) or (701/96,117,300,301)). CCLS. or ("704").CLAS.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	OFF	2005/11/01 10:31
L9	20854	8 and (recogni\$4 or detect\$4 or identif\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:31

L10	6618	9 and (camera\$3 or CCD or video\$3 or captur\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:37
[.15]	6260	10 and (calculat\$4 or comput\$4 or measur\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:32
L12	2945	11 and distanc\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:32
L13	1158	12 and target\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR.	ON	2005/11/01 10:32
L14	309	13 and compress\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:36

L15	119	14 and (vehicl\$4 or car or automobil\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:44
L16	55	15 and vertical\$3	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:34
L17	18	16 and lateral	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:37
L18	0	17 and parallax\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:34
L19	3996	8 and ((calculat\$4 or comput\$4 or measur\$4) near4 (distanc\$3))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:43

L20	204	19 and ((compress\$4) near4 (unit\$4 or apparatus or system or device))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:45
L21	85	20 and (camera\$3 or CCD or video\$3 or captur\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:43
L22	1	21 and (lateral\$3 near4 direction\$3)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:42
L23	7	21 and (lateral\$3 same direction\$3)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:40
L24	0	21 and gradation	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:46

L25	59	21 and extract\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:44
L26	43	25 and group\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:42
L27	280	8 and (lateral\$3 near4 direction\$3)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:42
L28	157	27 and ((calculat\$4 or comput\$4 or measur\$4) near4 (distanc\$3))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:43
L29	103	28 and (camera\$3 or CCD or video\$3 or captur\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:43

L30	101	29 and (vehicl\$4 or car or automobil\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:44
131	49	30 and extract\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:44
L32	1	31 and ((compress\$4) near4 (unit\$4 or apparatus or system or device))	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:45
L33	6	31 and gradation	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TDB	OR	ON	2005/11/01 10:46



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Key IEEE JNL IEEE CNF IEEE CNF IEEE SYD	IEEE Journal or Magazine IEEE Journal or Magazine IEEE Conference Proceeding IEEE Conference Proceeding IEEE Standard		Article Information  1. Smart cameras with real-tim Del Bue, A.; Comaniciu, D.; Rollmage Processing. 2002. Proc Volume 3, 24-28 June 2002 P Digital Object Identifier 10.110 AbstractPlus   Full Text: PDE(3)	e video object genera amesh, V.; Regazzoni, eedings. 2002 Internat lage(s):III-429 - III-432 9/ICIP.2002.1038997	<b>ition</b> C.; ional Conference on	
		n	2. Command, control and data Green, D.; Bernstein, C.; Underwater Technology, 2002 16-19 April 2002 Page(s):343 Digital Object Identifier 10.110	. Proceedings of the 20	ater robots using acoustic con	nmunication:

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L1	1	(target\$4 and (recogni\$4 or identif\$4 or detect\$4) and (video\$3 or CCD or captur\$ or cameras) and (calculat\$4 or comput\$4 or measur\$4) and compress\$4 and lateral and direction and vehicle). CLM.	US-PGPU B	AND	ON	2005/11/01 10:58